

# DF-150-32

## Absolute position, rotary Electric Encoder™

Encoders<sup>™</sup>, based on Netzer Precision proprietary technology. The Electric Encoder™ offers many advantages - some unparalleled

Low profile (13 mm). Hollow, floating shaft.

No bearings or other contacting elements.

High resolution and precision.

High tolerance to temperature extremes, shock, moisture, EMI, RFI and Magnetic fields.

Very low weight.

Holistic signal generation

Digital interfaces.

Mechanical	
Allowable mounting eccentricity	±0.1 mm
Allowable rotor axial motion	±0.1 mm
Rotor inertia	215,847 gr · mm²
Total weight	310 gr
Outer Ø /Inner Ø/ Height	150/110 / 13 mm
Material (stator, rotor)	Aluminum
Nominal air gap (stator, rotor)	0.6 mm

Electrical		
Supply voltage	5V ± 5%	
Interconnection	Shielded cable or	
Cable Length	1,500 mm MAX	
Environmental		
EMC	IEC 6100-6-2, IEC 6100-6-4	
Operating temperature range	Digital: -40°C to +85°C	
Relative humidity	98% Non condensing	
Shock endurance	100 g for 11 ms	
Vibration endurance	20 g 10 – 2000 Hz	
Protection	IP 40	

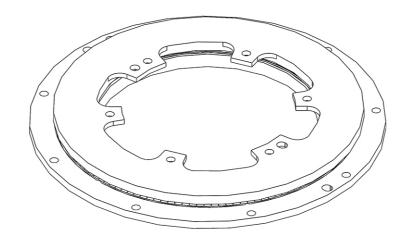
Characteristics	
Angular resolution	18 bits ; 262,144 CPR
Static error	< 10 mDeg
Maximum operational speed	750 rpm
Measurement range	Unlimited rotation
Build In Test BIT	Optional

The DF-150 is a member of the DF series of Electric The Electric Encoder™ is unique in being holistic, i.e., its output reading is the averaged outcome of the whole area of the rotor, This feature makes the Electric Encoder™ forgiving to mounting tolerances, mechanical wander etc. The absence of components such as ball bearings, flexible couplers, glass disc, light sources and detectors, along with very low power consumption makes the Electric Encoder™ virtually failure free.

> The internally shielded, DC operated Electric Encoder™ includes an electric field generator, a field receiver, a sinusoidal shaped dielectric rotor, and processing electronics.

> The output signals of Electric Encoder<sup>™</sup> are analog Sine / Cosine representing the rotation angle. The digital outputs are obtained by further processing - which may be either internal or external to the encoder.

> The combination of precision, low profile, low weight and high reliability have made Netzer Precision encoders particularly suitable to a wide variety of critical applications including, but not limited to medical equipment and aerospace.







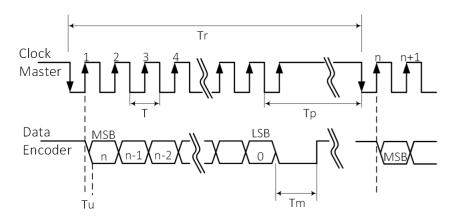
# DF-150-32

## Absolute position, rotary Electric Encoder™

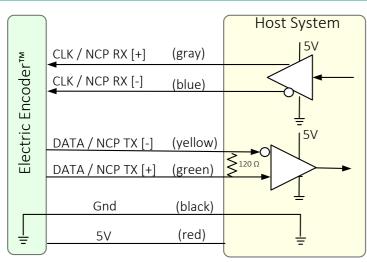


#### **Digital SSi Interface**

Synchronous Serial Interface (**SSI)** is a point to point serial interface standard between a master (e.g. controller) and a slave (e.g. sensor) for digital data transmission.



	Description	Recommendations	
n	Total number of data bits	12- 22	
T	Clock period		
f= 1/T	Clock frequency	0.5 - 2.0 MHz	
Tu	Bit update time	200 nsec	
Тр	Pause time	26 - ∞ µsec	
Tm	Monoflop time >25 µsec		
Tr	Time between 2 adjacent requests	Tr > n*T+26 µsec	
fr=1/Tr	Data request frequency		



SSi / BiSS Output signal parameters		
Signal latency	~250 µSec	
Output code	Binary	
Serial output	Differential RS-422	
Clock	Differential RS-422	
Clock Frequency	0.5 ÷ 2.0 MHz	
Position update rate (Max)	30 KHz	
Current consumption	180 mA	

SSi	
Monoflop time	25 μSec

SSi / BiSS interface wires color code			
Clock +	Grey	Clock	
Clock -	Blue		
Data -	Yellow	Data	
Data +	Green	Data	
GND	Black	Ground	
+5V	Red	Power supply	

**Software tools:** (SSi / BiSS - C)

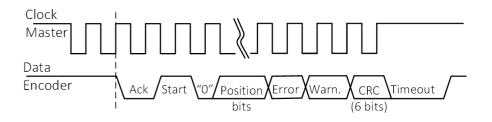
Advanced calibration and monitoring options are available by using the factory supplied **Electric Encoder Explorer** software, This facilitates proper mechanical mounting, offsets calibration and advanced signal monitoring.





#### **Digital BiSS-C Interface**

**BiSS – C** Interface is unidirectional serial synchronous protocol for digital data transmission where the Encoder acts as "slave" transmits data according to "Master" clock. The BiSS protocol is designed in B mode and C mode (continuous mode) .The BiSS–C interface as the SSi is based on RS-422 standards.

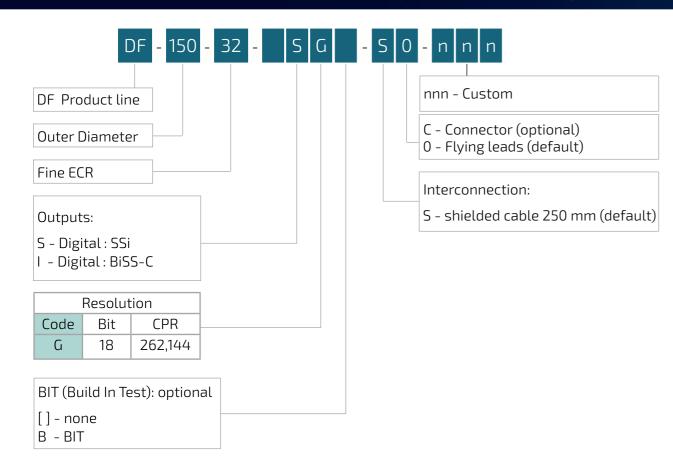


bit #		Description	Default	Length
28	Ack	Period during which the encoder calculates the absolute position , one clock cycle	0	1/clock
27	Start	Encoder signal for "start" data transmit	1	1 bit
26	"0"	"start" bit follower	0	1 bit
825	AP	Absolute Position encoder data		
7	Warn.	Warning	1	1 bit
6	Error	Error	1	1 bit
05	CRC	The CRC polynomial for position, error and warning data is: $x^6 + x^1 + x^0$ . It is transmitted MSB first and inverted. The start bit and "0" bit are omitted from the CRC calculation.		6 bits
	Timeout	Elapse between the sequential "start"request cycle's.		25 μs



# DF-150-32

# Absolute position, rotary Electric Encoder™



Pair#

1

Color

Red / Black

Gray / Blue

Green / Yellow

Netzer Cat No.: CB-00014

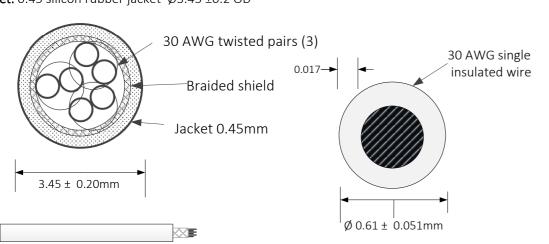
**Provider:** Ray-Q USA. wire CAT No: RQ213210

Cable: 30 AWG twisted pair (3) :2 (30 AWG 25/44 finned copper,

0.15 PFE to  $\emptyset$ 0.6  $\pm$  0.05 OD). Temperature rating: -60 to +150 Deg C.

Braided shield : Thinned copper braided 95% min. coverage.

Jacket: 0.45 silicon rubber jacket Ø3.45 ±0.2 OD



### Related documents:

DF-150 User Manual: Mechanical, Electrical and calibration

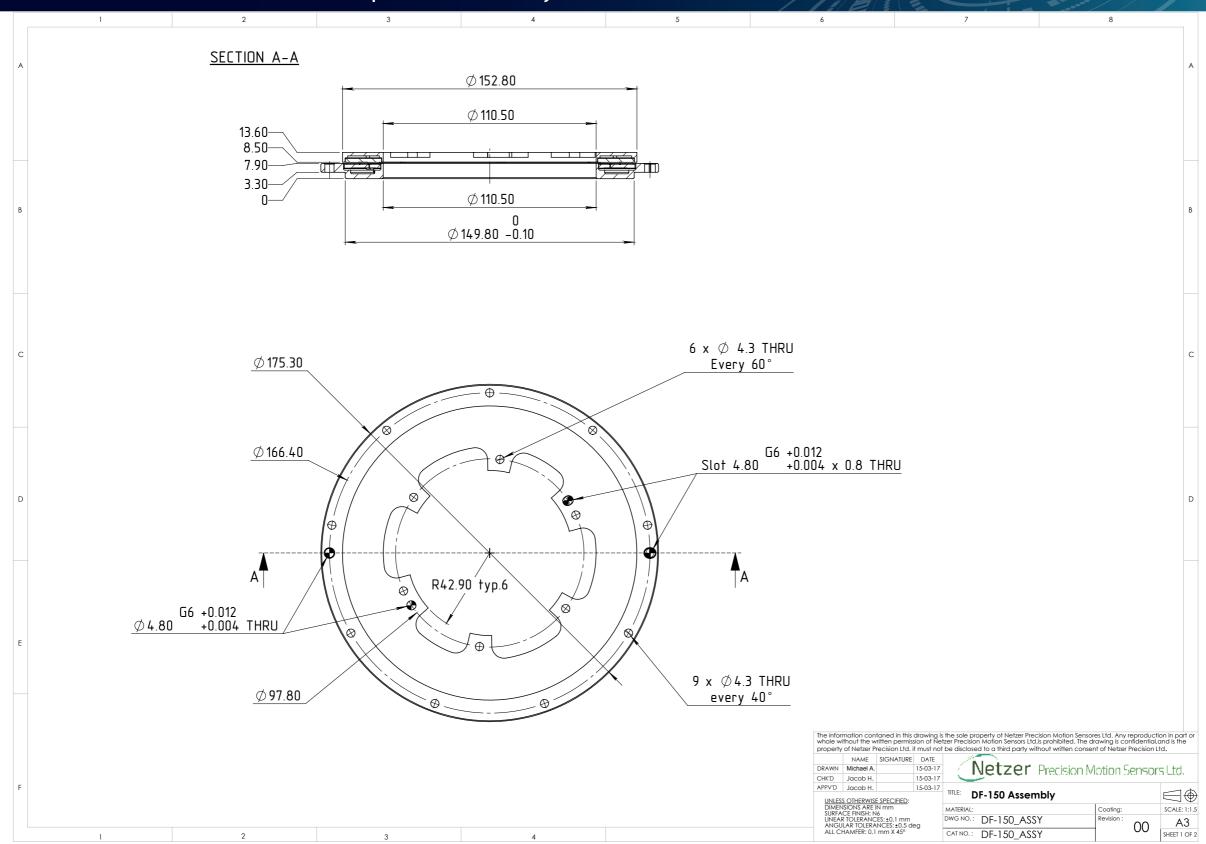
#### **Demonstration Kit:**

**DF-150DKIT-01:** Includes ,mounted encoder on rotary jig , and RS-422 to USB converter.

3



# DF-150-32 Absolute position, rotary Electric Encoder™





# DF-150-32 Absolute position, rotary Electric Encoder™

