

DL-25

Absolute position, rotary Electric Encoder™

The DL-25 is a member of the DL series of Electric Encoders™, based on Netzer Precision proprietary technology. The Electric Encoder™ offers many advantages - some unparalleled

High resolution and precision.
 High tolerance to temperature extremes , shock, moisture, EMI, RFI and Magnetic fields.
 Holistic signal generation
 Digital interfaces.
 IP65

The Electric Encoder™ is unique in being holistic, i.e., its output reading is the averaged outcome of the whole area of the rotor , This feature makes the Electric Encoder™ forgiving to mounting tolerances, mechanical wander etc. The absence of components such as ball bearings , flexible couplers, glass disc, light sources and detectors, along with very low power consumption makes the Electric Encoder™ virtually failure free.

The internally shielded, DC operated Electric Encoder™ includes an electric field generator, a field receiver, a sinusoidal shaped dielectric rotor, and processing electronics.

The output signals of Electric Encoder™ are analog Sine / Cosine representing the rotation angle. The digital outputs are obtained by further processing - which may be either internal or external to the encoder.

The combination of precision, low profile, low weight and high reliability have made Netzer Precision encoders particularly suitable to a wide variety of critical applications including, but not limited to medical equipment and aerospace.



Mechanical

Starting torque	30 x 10 ⁻⁴ N.m
Shaft radial force (max)	100 N
Total weight	25 gr
Outer diameter / profile	25 / 20 mm
Material (case, shaft)	Aluminum / Stainless steel

Electrical

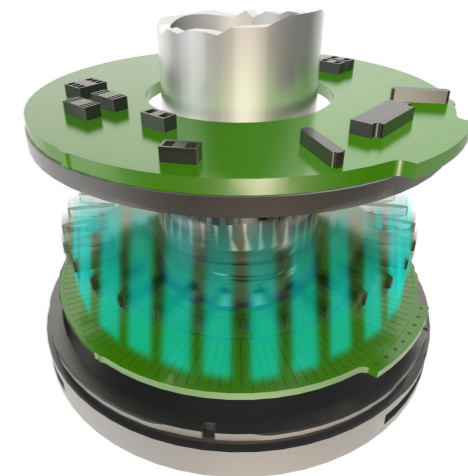
Supply voltage	5V ± 5%
Interconnection	Shielded cable or
Cable Length	1,500 mm MAX

Environmental

EMC	IEC 6100-6-2, IEC 6100-6-4
Operating temperature range	Digital: -40°C to +85°C
Relative humidity	98% Non condensing
Shock endurance	100 g for 11 ms
Vibration endurance	20 g 10 – 2000 Hz
Protection	IP 65

Characteristics

Angular resolution	17 bits ; 131,072 CPR
Static error	< 40 mDeg
Maximum operational speed	1,500 rpm
Measurement range	Unlimited rotation
Power On - Max. operational speed	3.3 RPM , <=20°/sec
Build In Test BIT	Optional



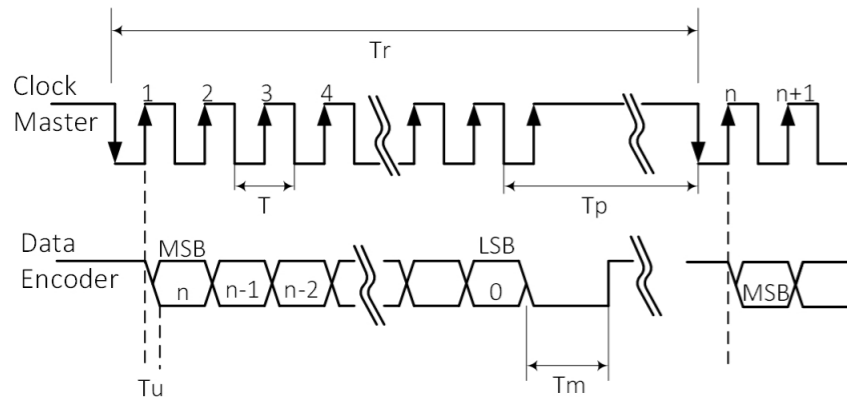


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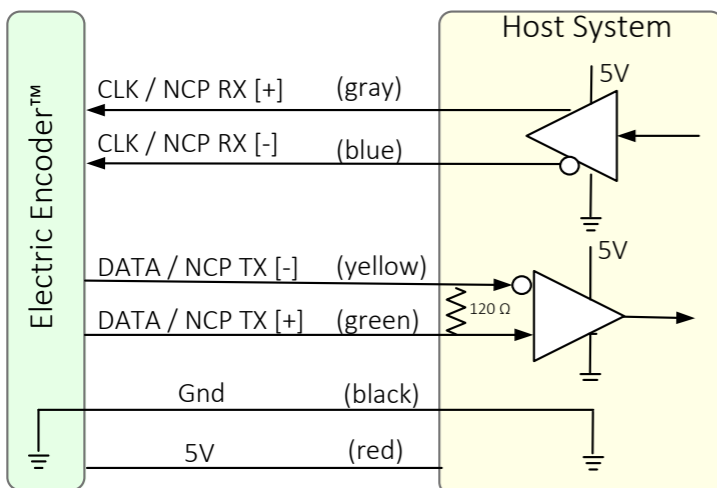


Digital SSI Interface

Synchronous Serial Interface (**SSI**) is a point to point serial interface standard between a master (e.g. controller) and a slave (e.g. sensor) for digital data transmission.



	Description	Recommendations
n	Total number of data bits	12- 22
T	Clock period	
f= 1/T	Clock frequency	0.5 - 2.0 MHz
Tu	Bit update time	200 nsec
Tp	Pause time	26 - ∞ μsec
Tm	Monoflop time	>25 μsec
Tr	Time between 2 adjacent requests	Tr > n*T+26 μsec
fr=1/Tr	Data request frequency	



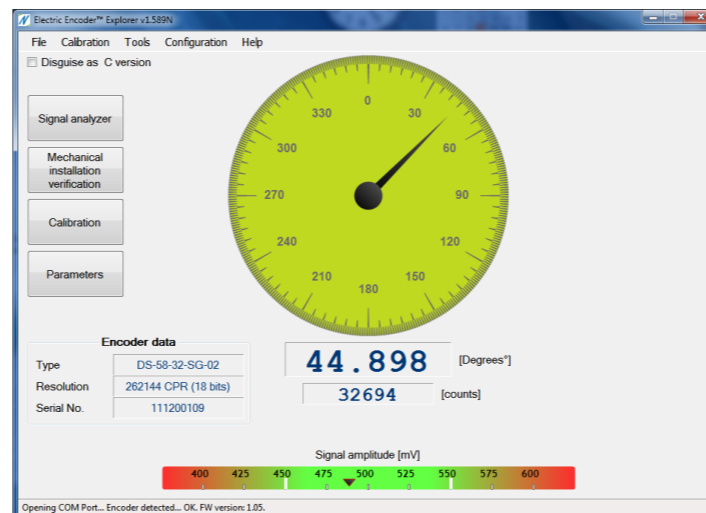
SSI / BiSS Output signal parameters	
Signal latency	~250 μSec
Output code	Binary
Serial output	Differential RS-422
Clock	Differential RS-422
Clock Frequency	0.5 ÷ 2.0 MHz
Position update rate (Max)	30 KHz
Current consumption	180 mA

SSI	
Monoflop time	25 μSec

SSI / BiSS interface wires color code		
Clock +	Grey	Clock
Clock -	Blue	
Data -	Yellow	Data
Data +	Green	
GND	Black	Ground
+5V	Red	Power supply

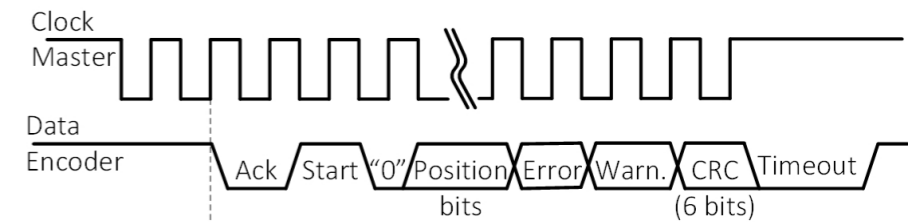
Software tools: (SSI / BiSS - C)

Advanced calibration and monitoring options are available by using the factory supplied **Electric Encoder Explorer** software, This facilitates proper mechanical mounting, offsets calibration and advanced signal monitoring.



Digital BiSS-C Interface

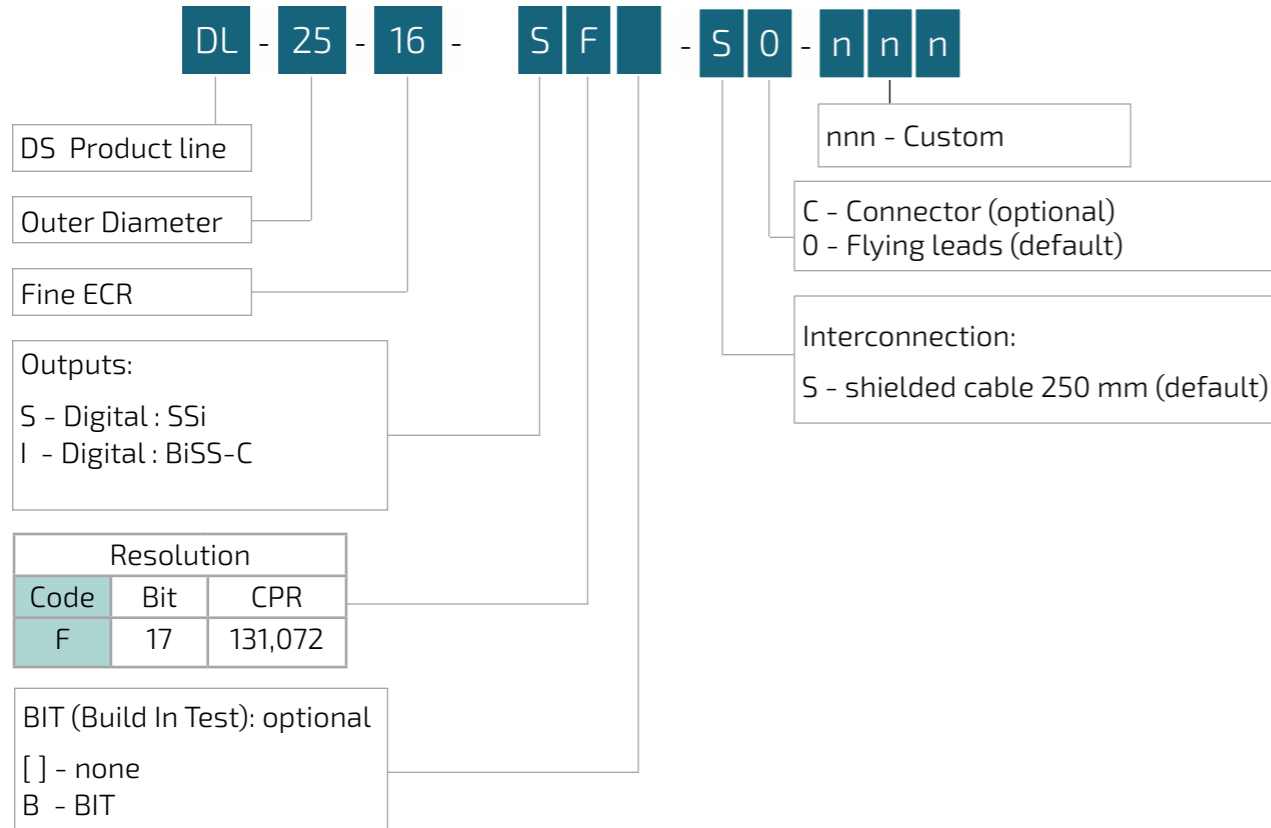
BiSS - C Interface is unidirectional serial synchronous protocol for digital data transmission where the Encoder acts as "slave" transmits data according to "Master" clock. The BiSS protocol is designed in B mode and C mode (continuous mode) .The BiSS-C interface as the SSI is based on RS-422 standards.



bit #		Description	Default	Length
27	Ack	Period during which the encoder calculates the absolute position , one clock cycle	0	1/clock
26	Start	Encoder signal for "start" data transmit	1	1 bit
25	"0"	"start" bit follower	0	1 bit
8...24	AP	Absolute Position encoder data		
7	Warn.	Warning	1	1 bit
6	Error	Error	1	1 bit
0...5	CRC	The CRC polynomial for position, error and warning data is: $x^6 + x^1 + x^0$. It is transmitted MSB first and inverted. The start bit and "0" bit are omitted from the CRC calculation.		6 bits
	Timeout	Elapse between the sequential "start" request cycle's.		25 μs



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Netzer Cat No.: CB-00014

Provider: Ray-Q USA. wire CAT No: RQ213210

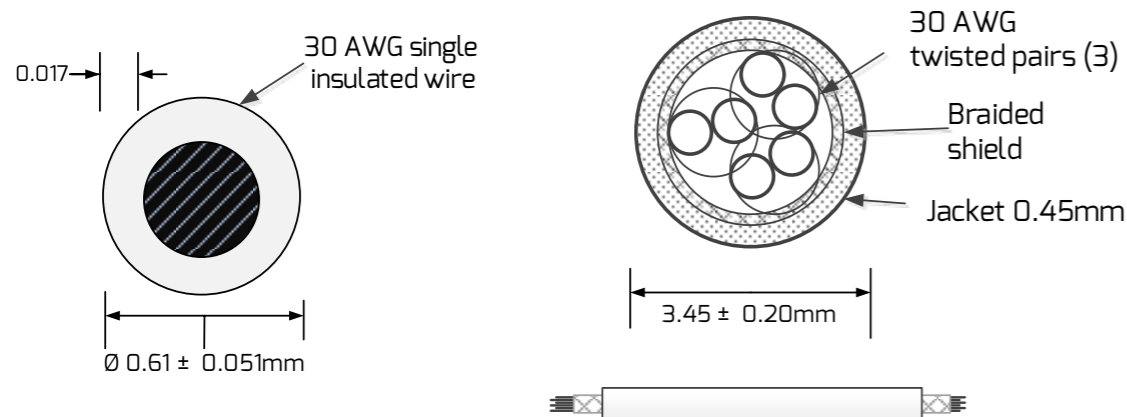
Cable: 30 AWG twisted pair (3) :2 (30 AWG 25/44 finned copper , 0.15 PFE to Ø0.6 ± 0.05 OD).

Temperature rating: -60 to +150 Deg C.

Braided shield: Thinned copper braided 95% min. coverage.

Jacket: 0.45 silicon rubber jacket Ø3.45 ± 0.2 OD

Pair #	Color
1	Red / Black
2	Gray / Blue
3	Green / Yellow



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